

Figure 1 Flight Path Intercept Procedures

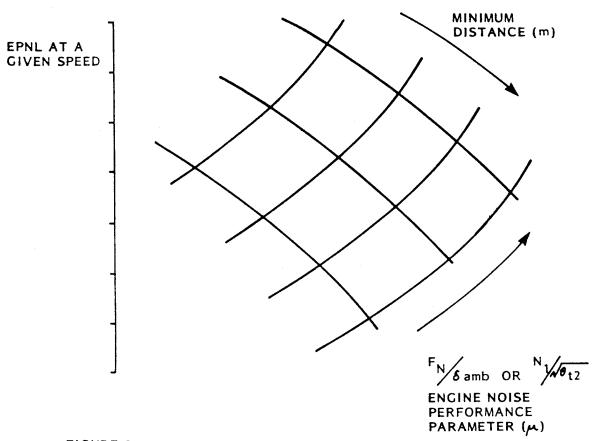


FIGURE 2
Form of NPD plot for turbo-jet or turbo-fan powered aeroplanes

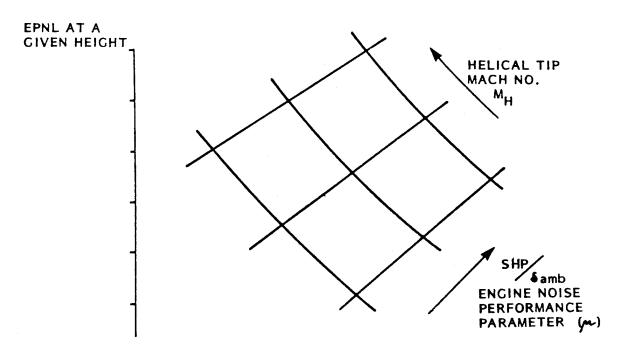


FIGURE 3
Form of NPD plot for propeller driven heavy aeroplanes

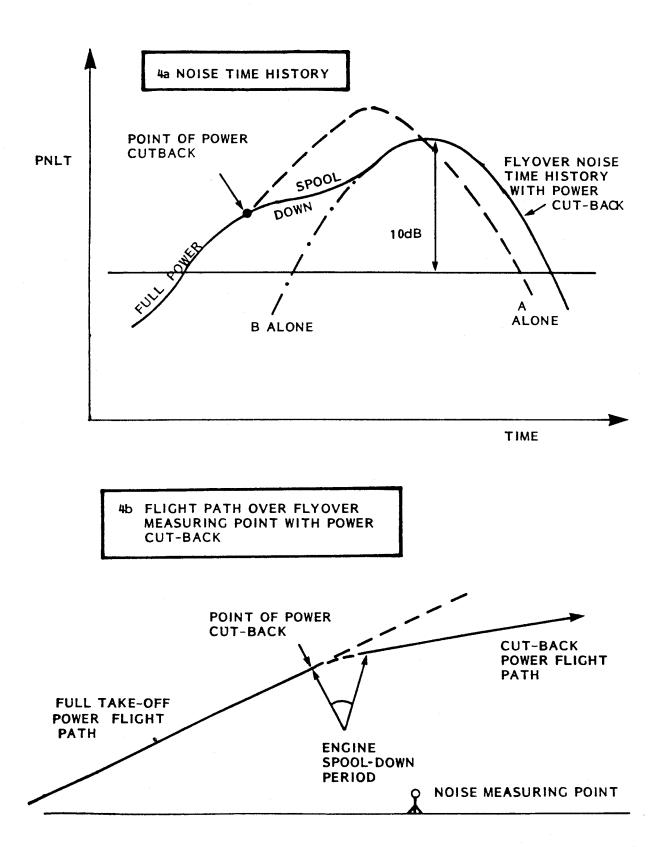
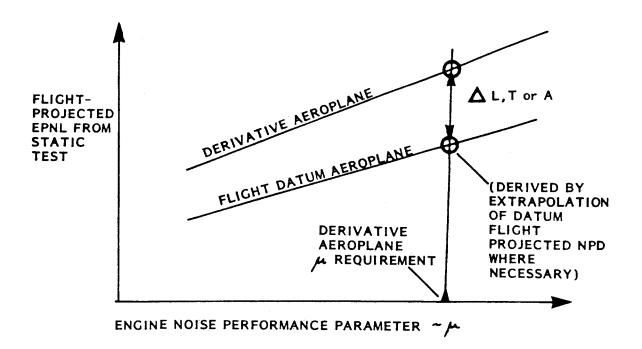


FIGURE 4

Computation of cutback-takeoff noise level from constant power tests



## **DEFINITIONS**

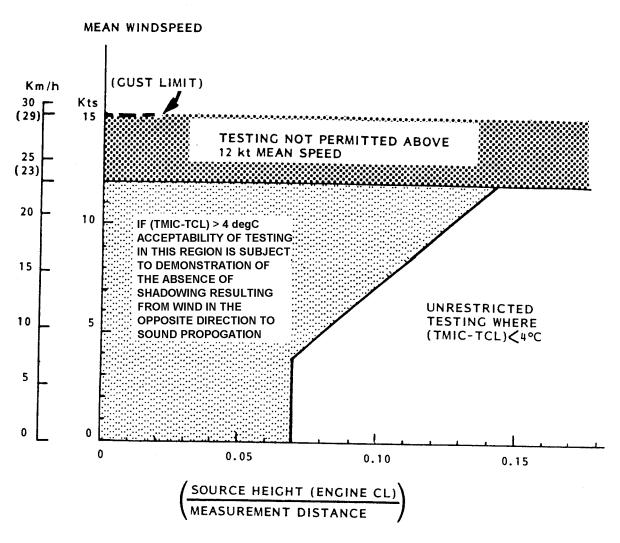
- L = DIFFERENCE BETWEEN FLIGHT DATUM AND DERIVATIVE AEROPLANE EPNL AT THE POWER REQUIREMENT OF THE DERIVATIVE AEROPLANE AT THE LATERAL CONDITION
- T = DIFFERENCE BETWEEN FLICHT DATUM AND DERIVATIVE AEROPLANE EPNL AT THE POWER REQUIREMENT AND ALTITUDE OF THE DERIVATIVE AEROPLANE AT THE TAKE-OFF CONDITION.
- A = DIFFERENCE BETWEEN FLIGHT DATUM AND DERIVATIVE AEROPLANE EPNL AT THE POWER REQUIREMENT OF THE DERIVATIVE AEROPLANE AT THE APPROACH CONDITION.

## **LIMITATIONS**

(i) 
$$\triangle L + \triangle T + \triangle A$$
 SHALL NOT EXCEED 5 EPNdB  
(ii)  $\triangle L$ ,  $\triangle T$  or  $\triangle A$  SHALL NOT EXCEED ±3 EPNdB INDIVIDUALLY.

## FIGURE 5

Limitation on the use of static test where no validating flight test data exist



NOTE

TCL = TEMPERATURE AT ENGINE CENTRELINE HEIGHT

TMIC = TEMPERATURE WITHIN ±5MM OF GROUND MICROPHONE DIAPHRAGM HEIGHT

FIGURE 6
Weather criteria for use with ground microphone installations

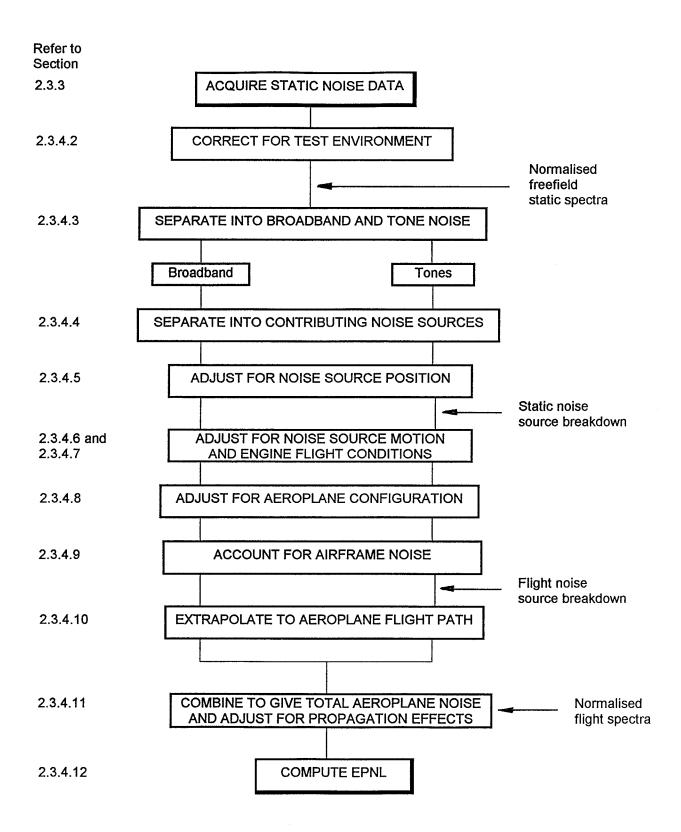


Figure 7
Generalised projection of static engine data to aeroplane flight conditions

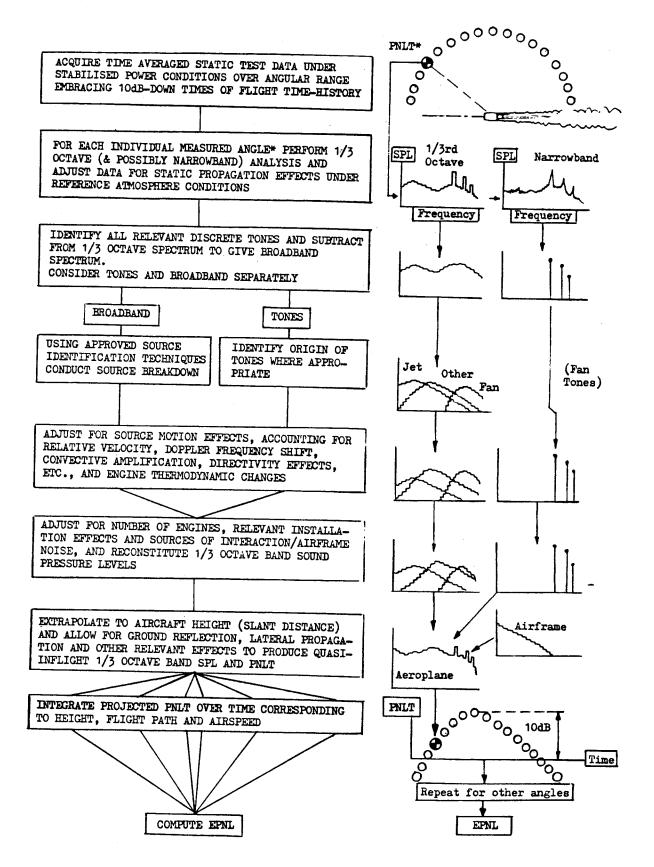


Figure 8
Example procedure for projection of static engine data to aeroplane flight conditions

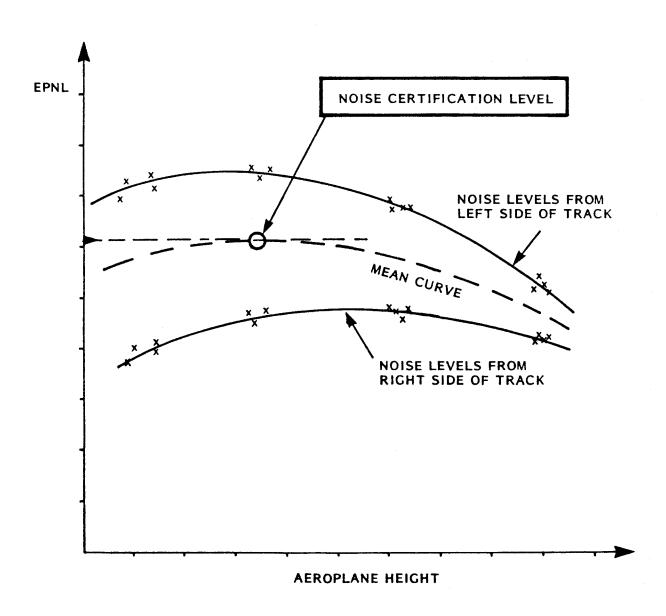


FIGURE 9

Typical lateral noise data plot for a propeller driven heavy aeroplane

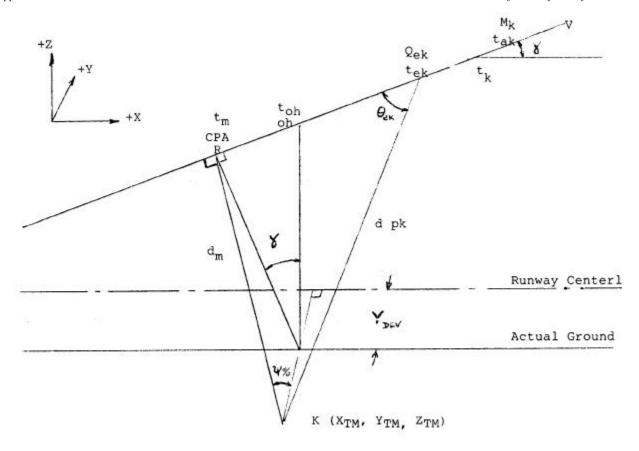


FIGURE 10 GEOMETRY FOR INTEGRATED PROCEDURE

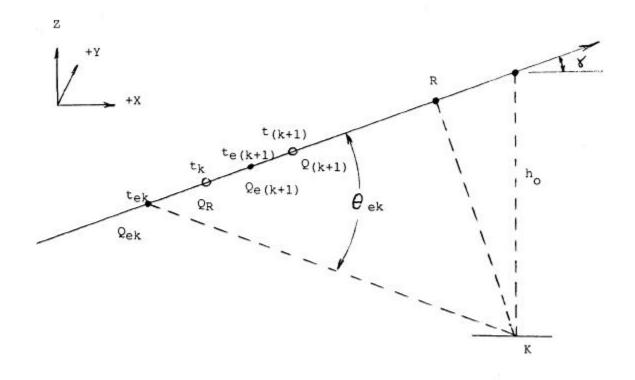


FIGURE 11 RELATIVE TIME PERIODS FOR INTEGRATED PROCEDURE

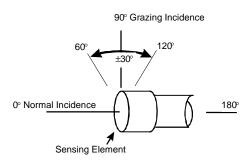
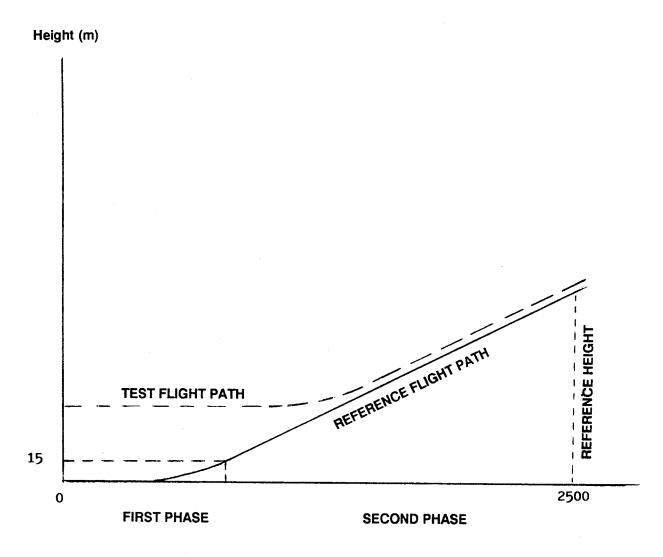


Figure 12 : Illustration of sound incidence angles on a microphone



Distance from Brake Release (m)

Figure 13 Typical Test and Reference Procedures

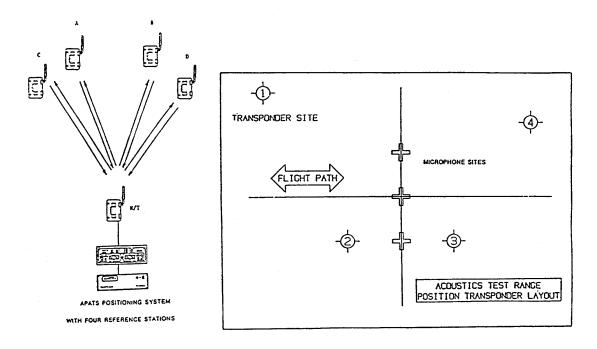
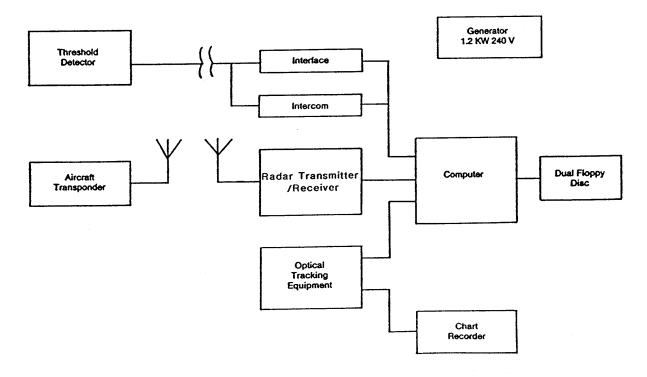
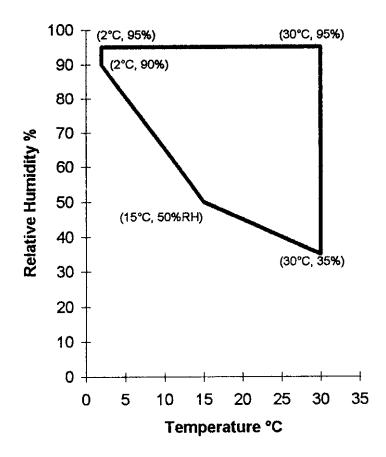


Figure 16 Radar Position Tracking System

Figure 17 Radar/optical Position Tracking System





Annex 16, Chapter 8 "zero attenuation adjustment window" FIGURE 16

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